

# A Generative Perspective on MRFs in Low-Level Vision



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Qi Gao



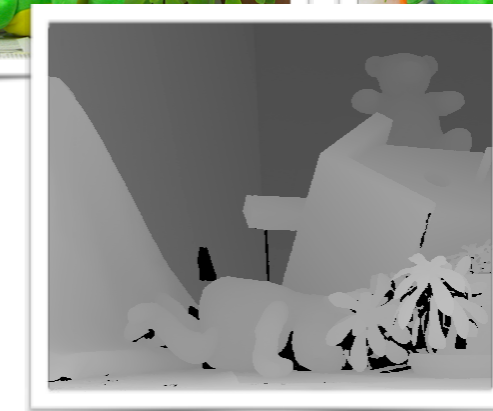
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# Low-Level Vision

Super-Resolution



Stereo

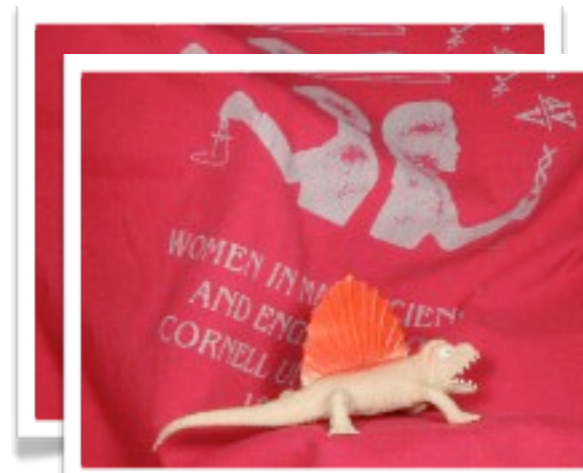
Discriminative

- ✓ performance
- ✗ versatility

Generative

- ✓ versatility
- ✗ learning

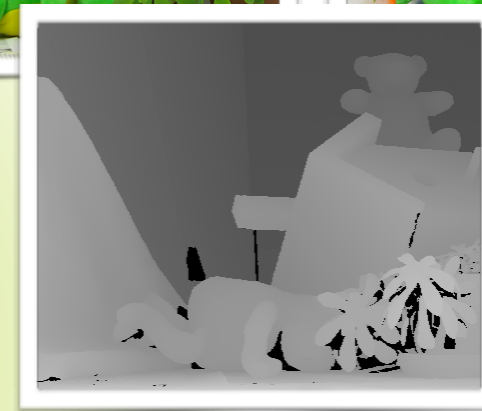
Image Restoration



Optical Flow

# Low-Level Vision

Super-Resolution

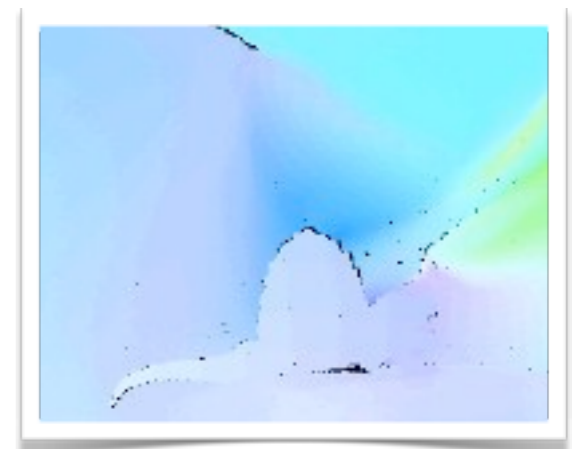


Stereo

Generative  
**MRF**  
Priors

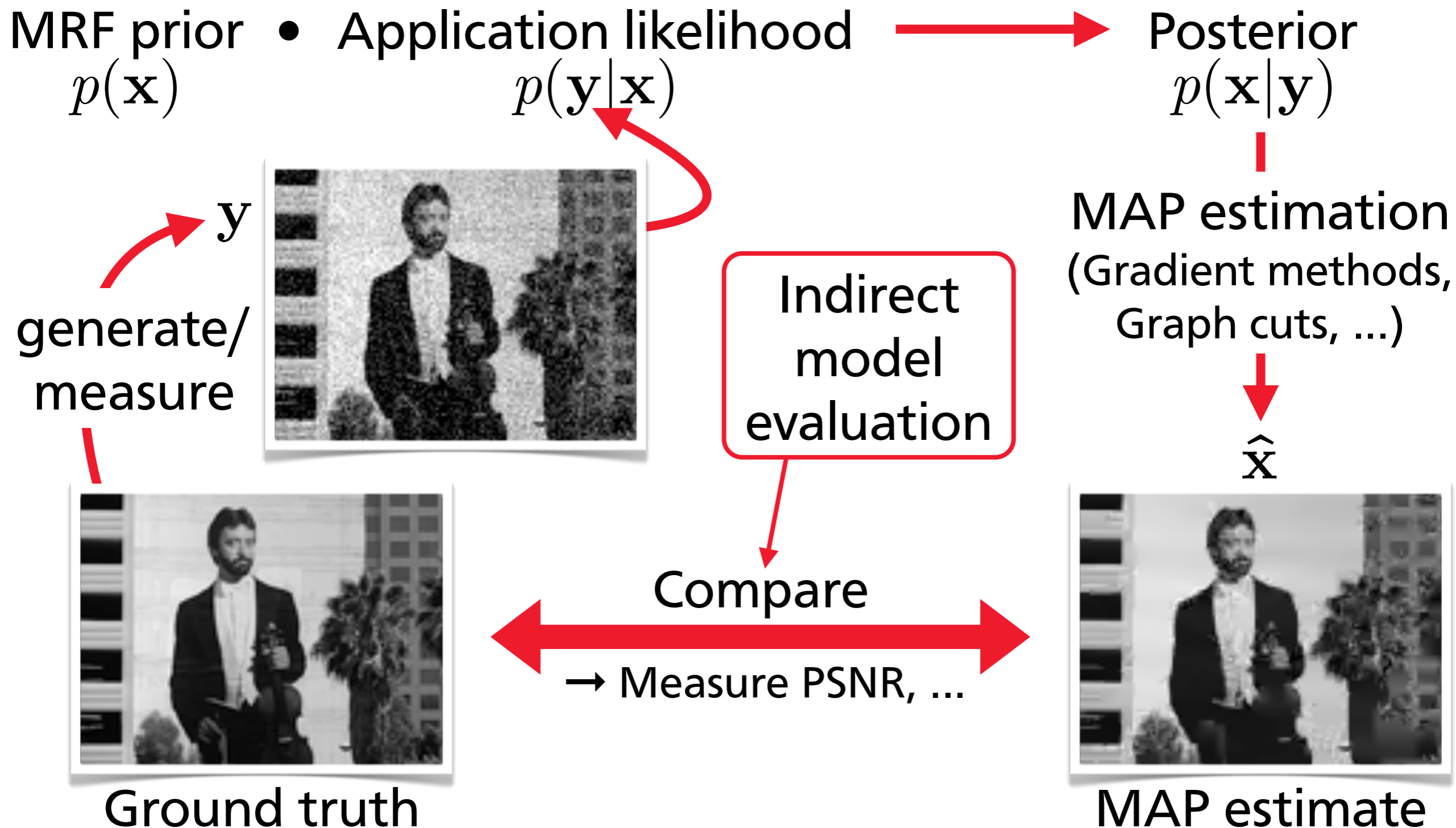


Image  
Restoration



Optical Flow

# Common MRF Evaluation



# Desirable MRF Evaluation

- Purpose of MRF priors
  - Model statistical properties of natural images and scenes
- ➔ Evaluate generative properties [Zhu & Mumford '97]
  - e.g. derivative statistics of the model
  - neglected ever since

Difficult!

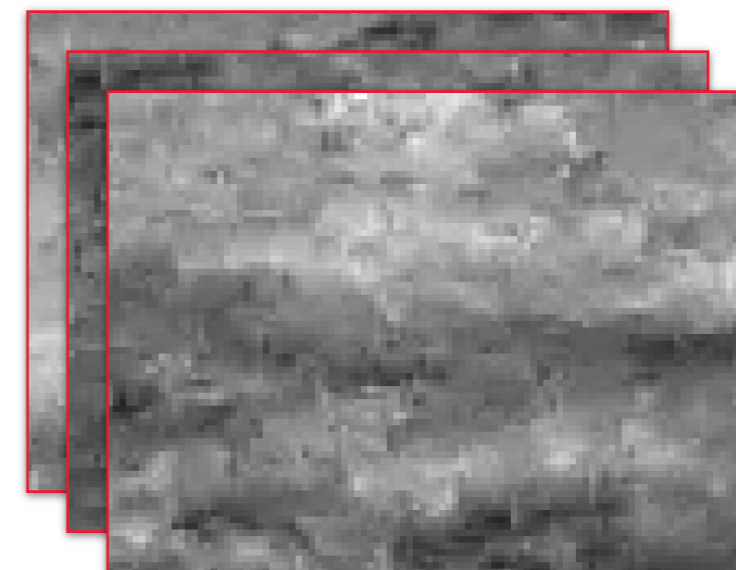
MRF prior

Draw samples  
(MCMC)



Data

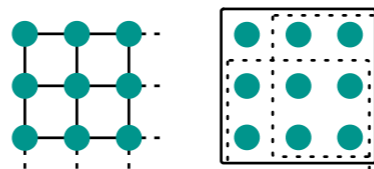
Compare  
statistical properties



MRF samples

## 1. Evaluate generative properties of common image priors

- Pairwise & high-order MRFs



- Based on a flexible MRF framework with an efficient sampler

## 2. Learn improved generative models

## 3. Find that in the context of MAP estimation our models do not perform as well as expected for image denoising

## 4. Address this problem (and others) by changing the estimator

# Flexible MRF Model

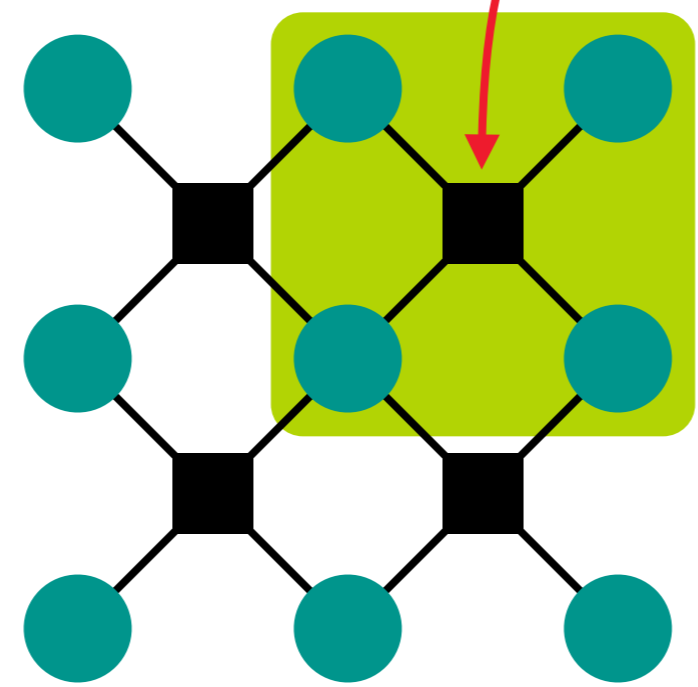
- Fields-of-Experts (FoE) framework [Roth & Black '05, '09]
  - Subsumes popular pairwise & high-order MRFs

$$p(\mathbf{x}; \Theta) = \frac{1}{Z(\Theta)} e^{-\epsilon \|\mathbf{x}\|^2 / 2} \prod_{c \in \mathcal{C}} \prod_{i=1}^N \phi(\mathbf{J}_i^T \mathbf{x}_{(c)}; \alpha_i)$$


Image

Parameters

$$\Theta = \left\{ \mathbf{J}_i, \alpha_i \right\}_{i=1, \dots, N}$$



Expert function

Linear filter  
e.g. 

Vector of nodes in clique  $c$



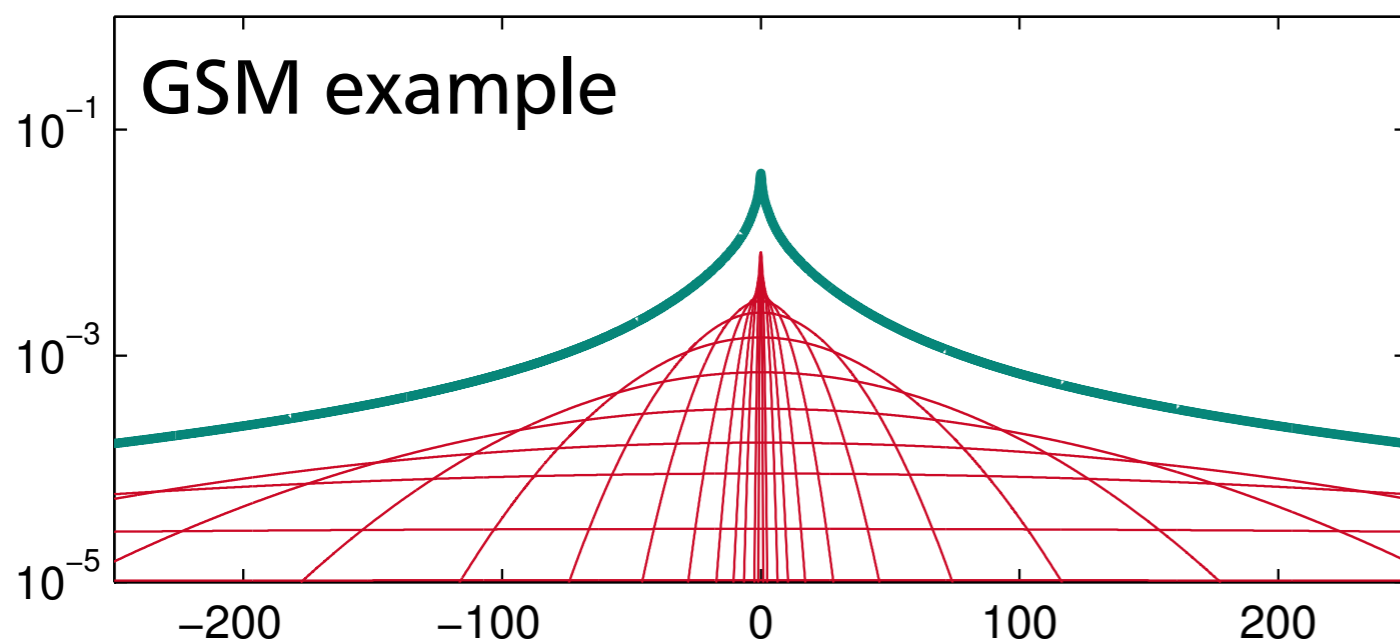
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- Fields-of-Experts (FoE) framework [Roth & Black '05, '09]
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Mixture Weights

$$\phi(\mathbf{J}_i^T \mathbf{x}_{(c)}; \alpha_i)$$



Gaussian Scale Mixture (GSM) Distribution

[Wainwright & Simoncelli '99, Weiss & Freeman '07]

$$\phi(\mathbf{J}_i^T \mathbf{x}_{(c)}; \alpha_i) = \sum_{j=1}^J \alpha_{ij} \cdot \mathcal{N}(\mathbf{J}_i^T \mathbf{x}_{(c)}; 0, \sigma_i^2 / s_j)$$



# Sampling from the MRF

- Obtain joint distribution:

- Product of GSMs = GSM
- Augment MRF with auxiliary variables  $\mathbf{z}$  for the mixture components and do not marginalize them out

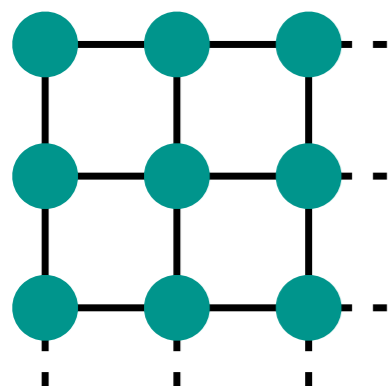
Mixture Weights

Gaussian

$$\sum_{\mathbf{z}} \underbrace{p(\mathbf{z}) p(\mathbf{x}|\mathbf{z})}_{p(\mathbf{x}, \mathbf{z})}$$

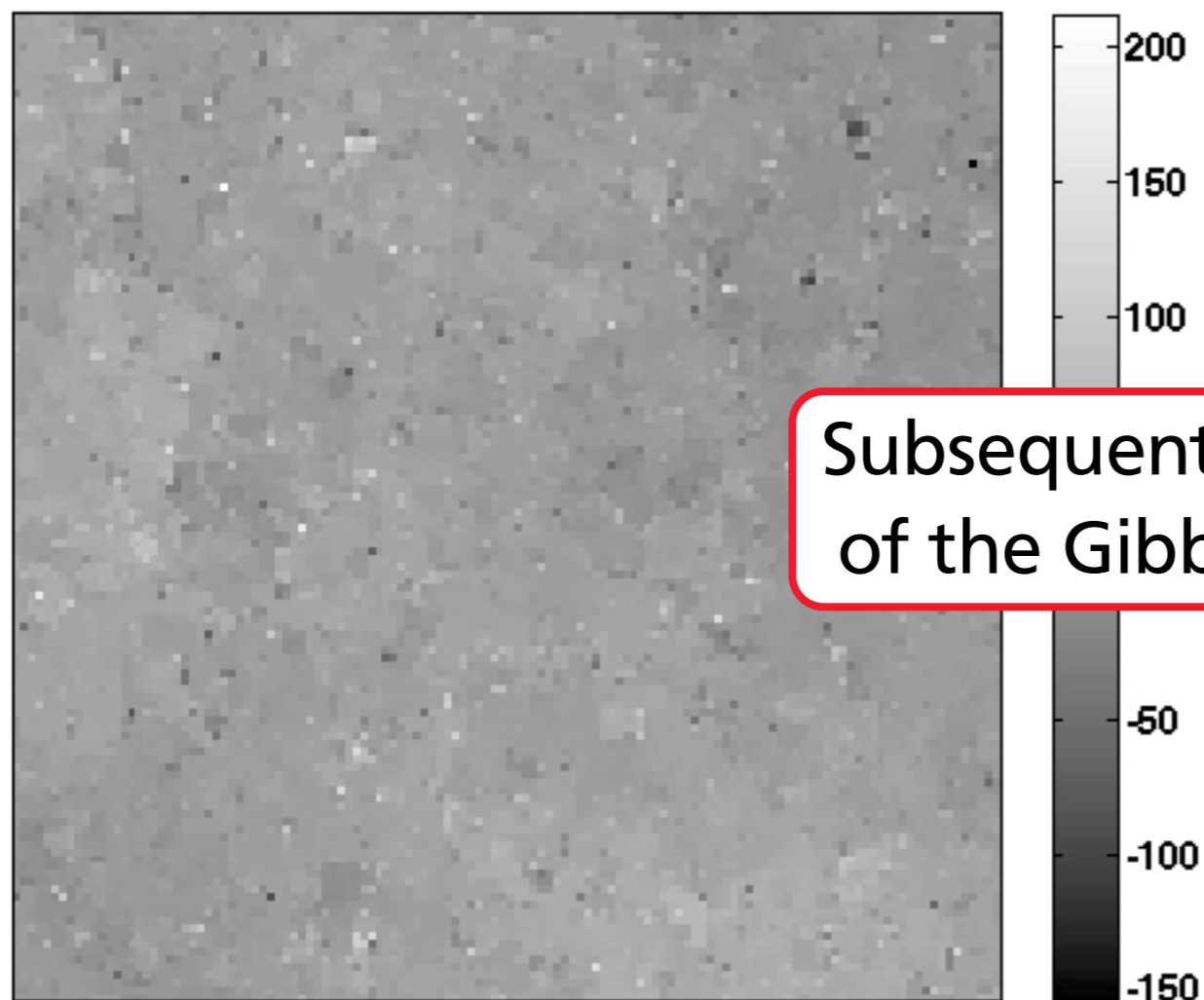
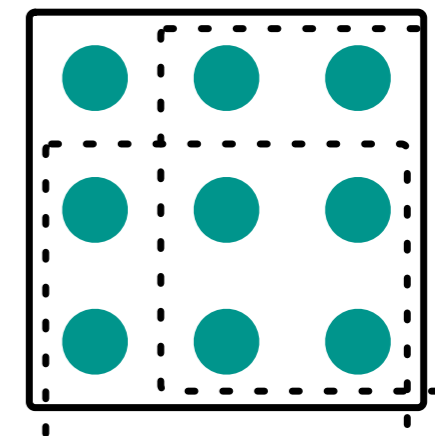
- Gibbs sampling from the joint distribution  $p(\mathbf{x}, \mathbf{z}; \Theta)$  [Geman & Yang '95; Welling et al. '02]
  - Alternate block sampling from  $p(\mathbf{x}|\mathbf{z}; \Theta)$  and  $p(\mathbf{z}|\mathbf{x}; \Theta)$
  - The  $\mathbf{z}$  can be discarded in the end
  - Least-squares method for sampling  $p(\mathbf{x}|\mathbf{z}; \Theta)$  [Weiss '05, Levi '09]

# MRF Sampling – Example

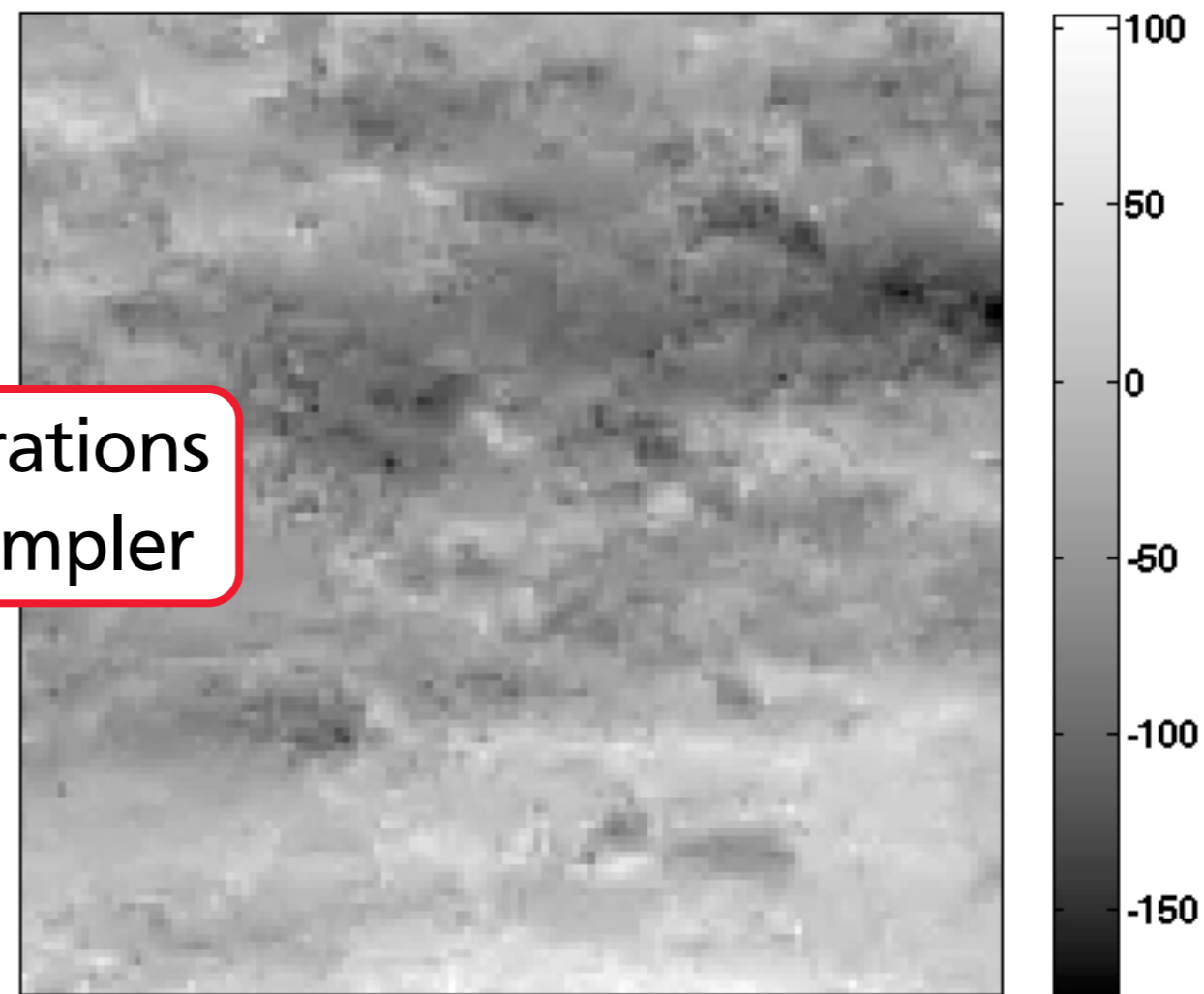


Pairwise MRF

High-order MRF  
with  $3 \times 3$  cliques

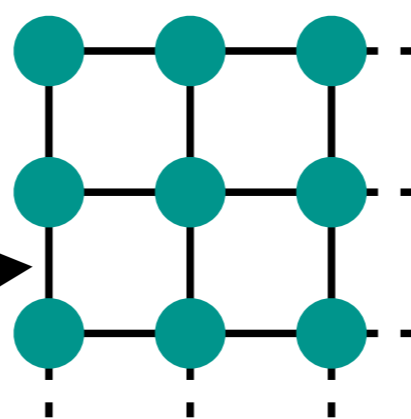


Subsequent iterations  
of the Gibbs sampler

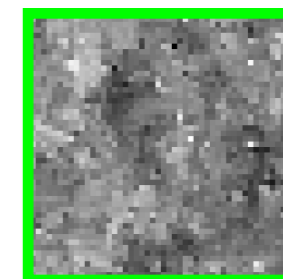
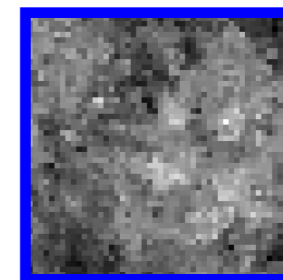


# Generative Properties of Pairwise MRFs

- Consider simplest pairwise MRFs

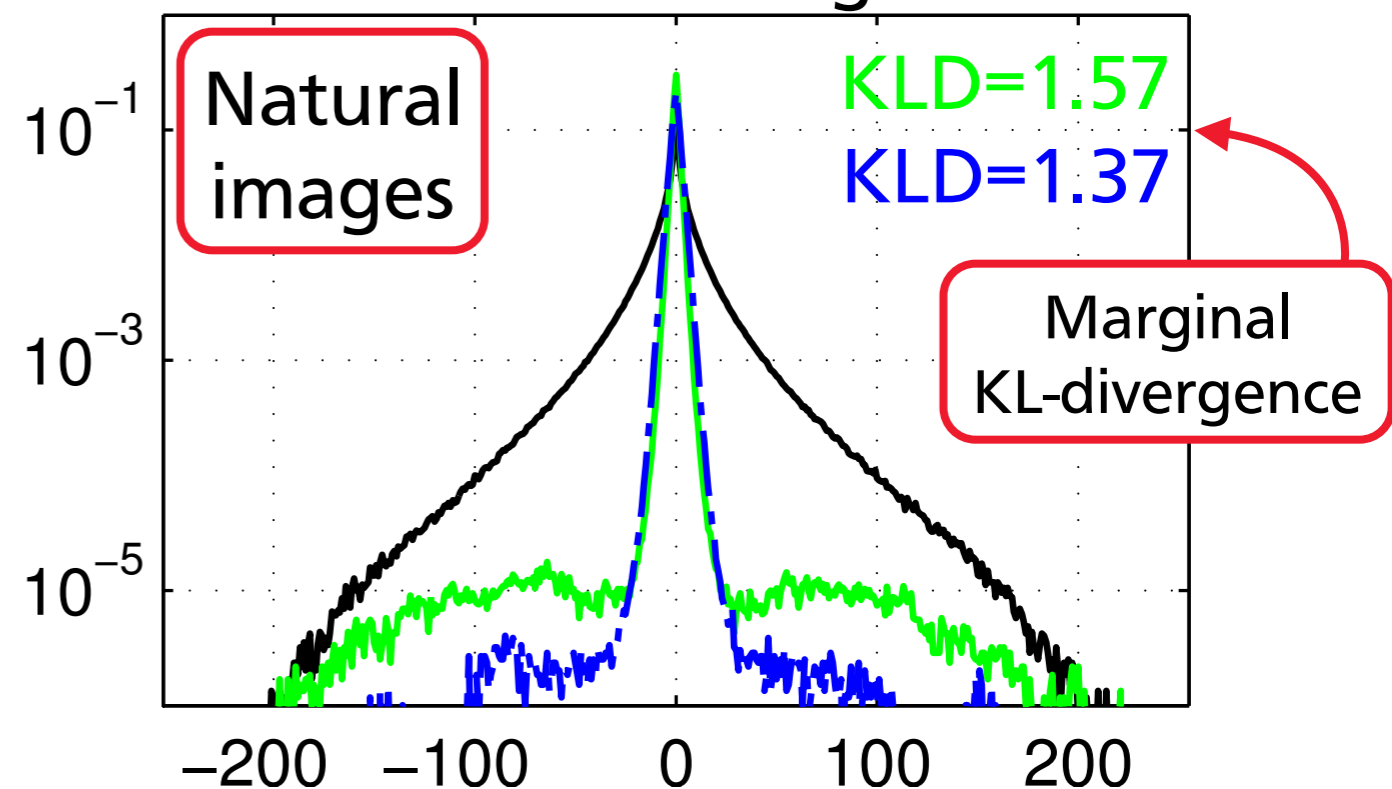
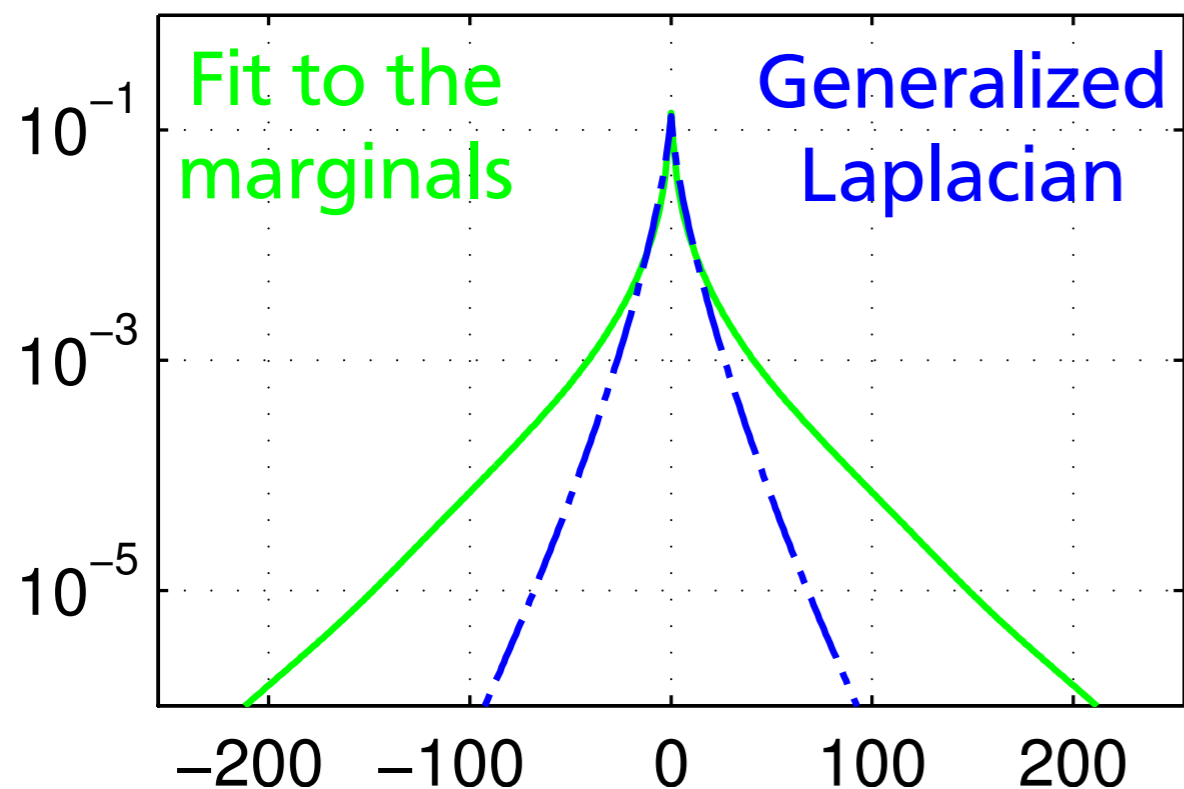


MRF



Potential function

Derivative marginals



# Generative Properties of High-order MRFs

- Common FoE models

- Evaluate filter statistics of model filters  $\mathbf{J}_i$

- Apparent contradiction:

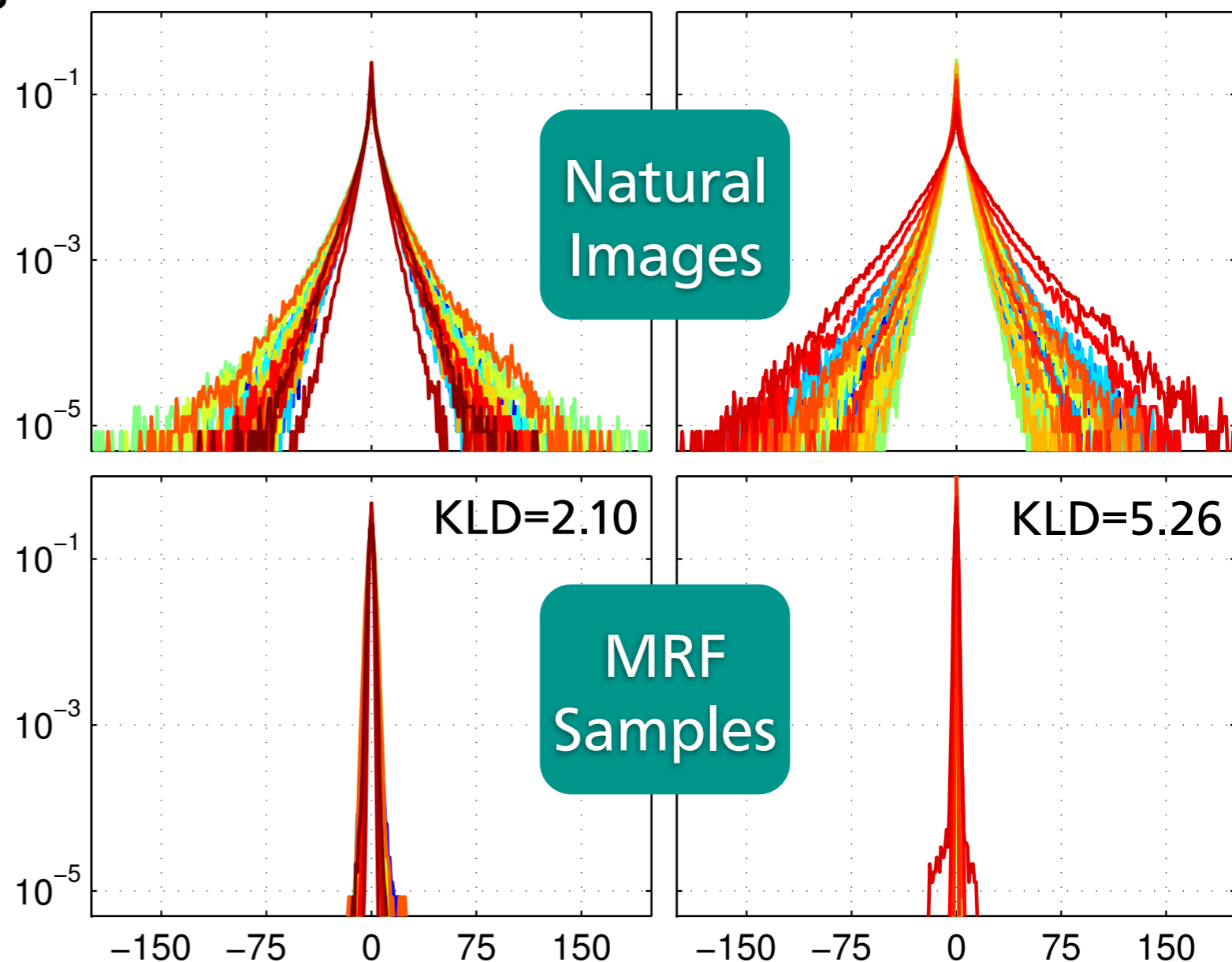
- ✗ Poor generative properties

- ✓ Good application performance

Why?

[Roth & Black '09]  
24 5×5 filters  
Student-t experts

[Weiss & Freeman '07]  
25 15×15 filters  
fixed GSM experts

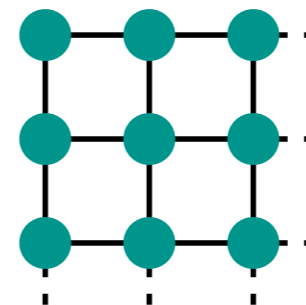


# Learning Better Generative MRFs

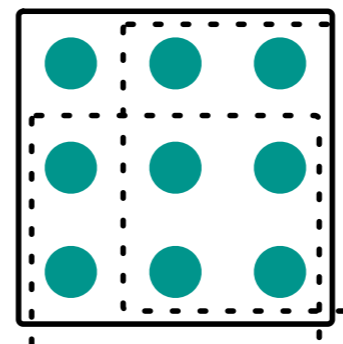
- Learn **shapes** of **flexible** GSM experts and linear filters  $J_i$  (for high-order model)
  - Use efficient sampler
  - Otherwise training similar to [Roth & Black '09]

- Learned models:

1. Pairwise MRF with single GSM potential (fixed first-derivative filters)

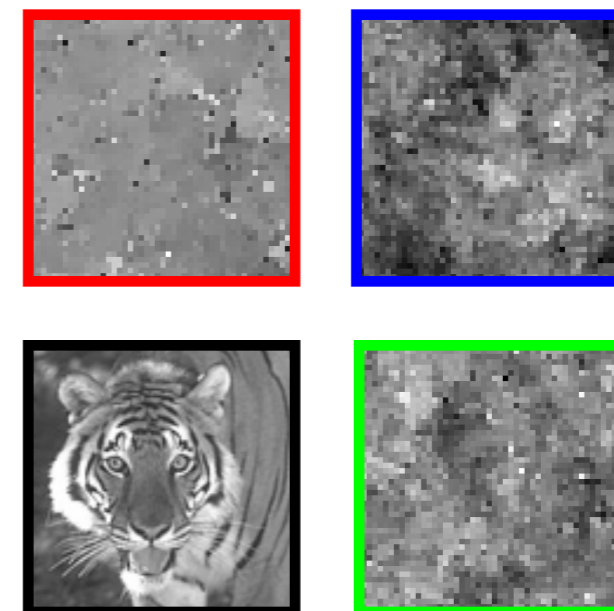
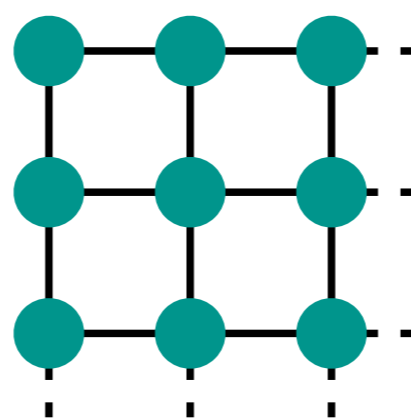


2. FoE with  $3 \times 3$  cliques and 8 GSM experts (including filters)



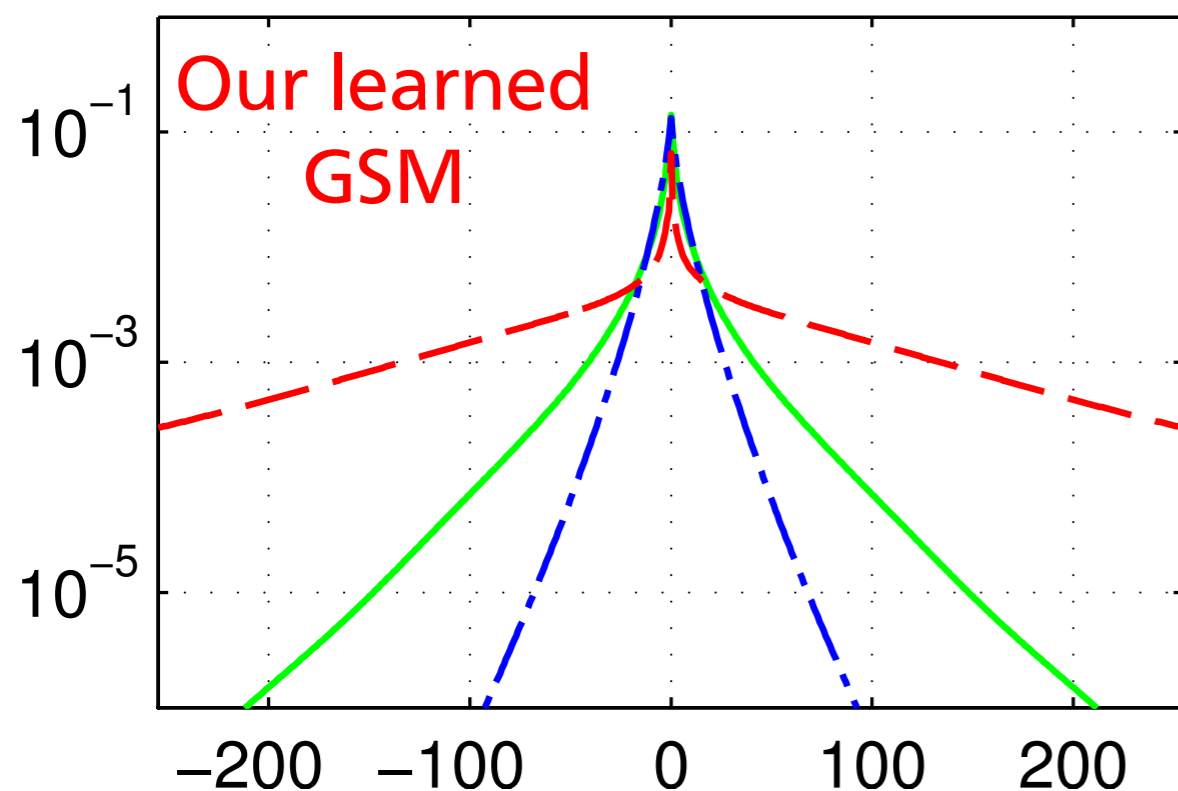
# Generative Properties of Our Pairwise MRF

- Our pairwise MRF compared to previously shown

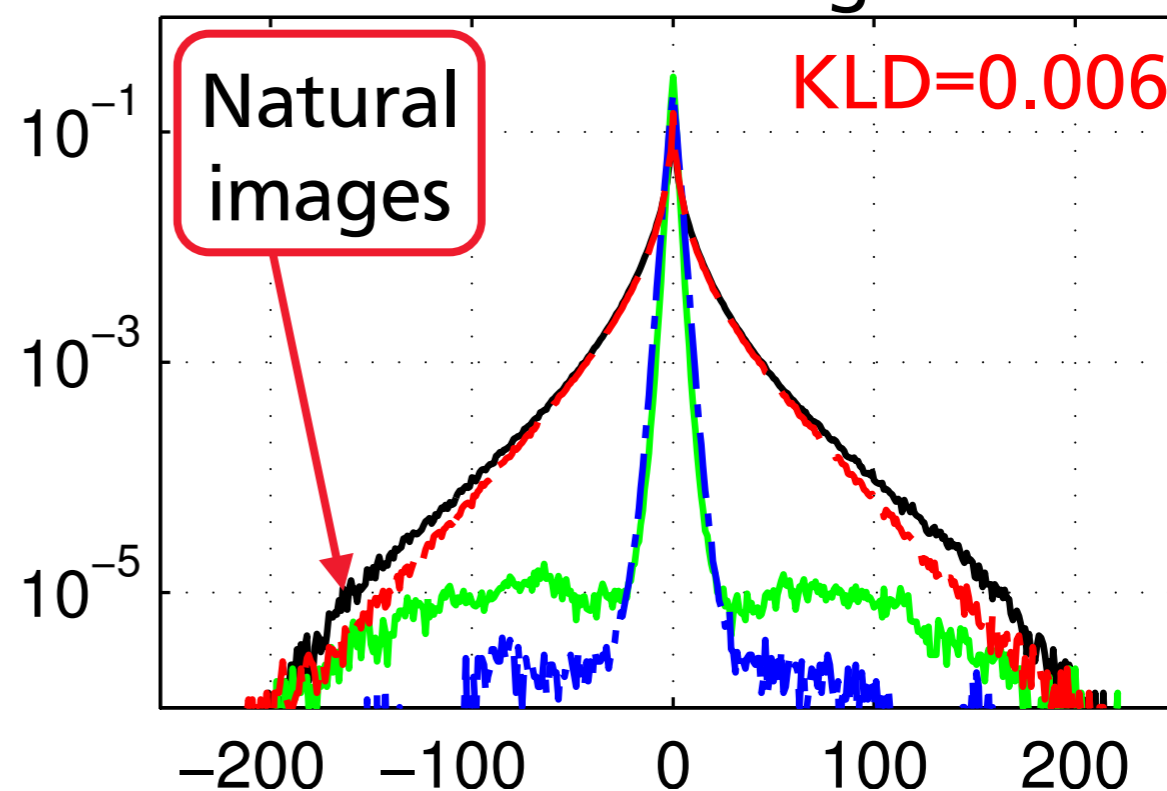


MRF

Potential function

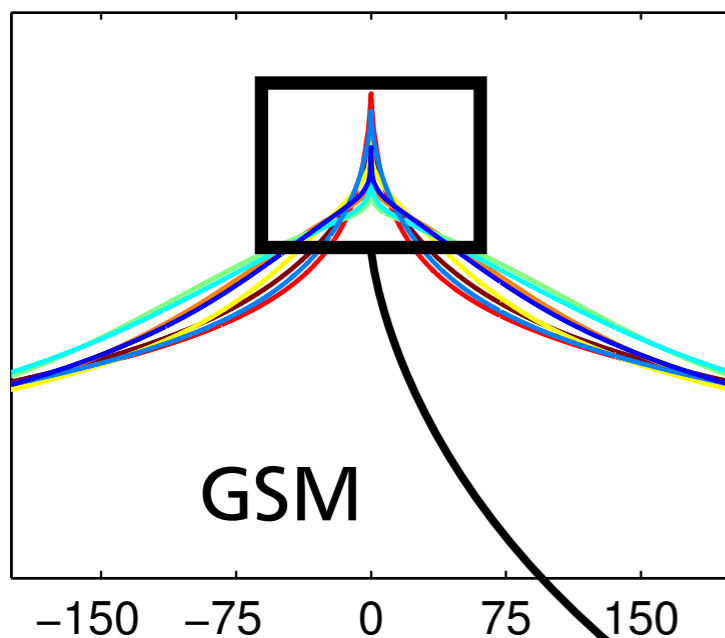


Derivative marginals

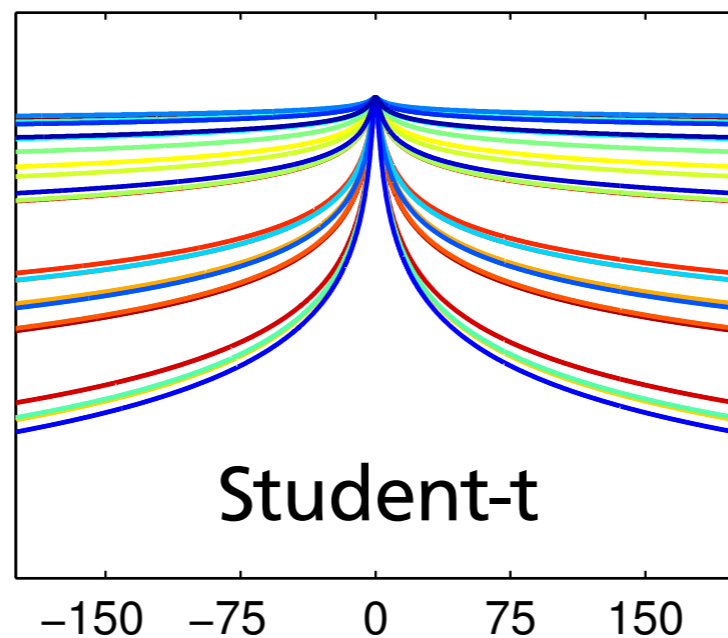


# Our Learned FoE in Comparison

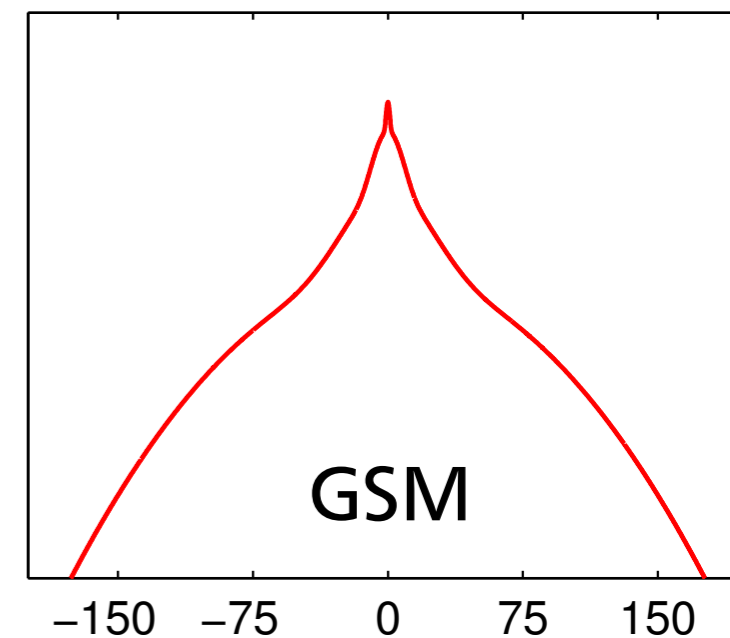
Our learned 3×3 FoE



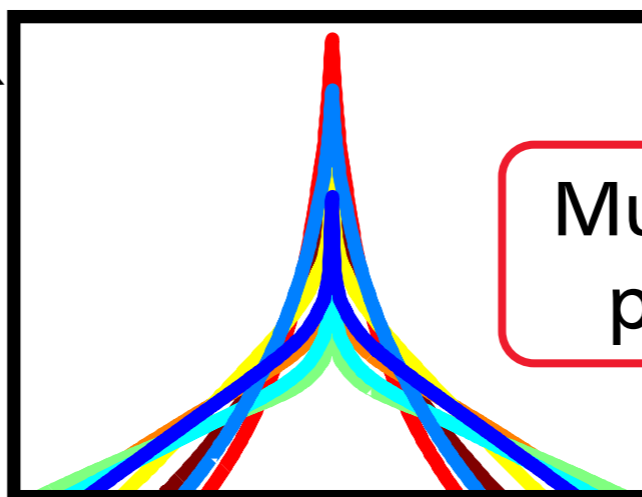
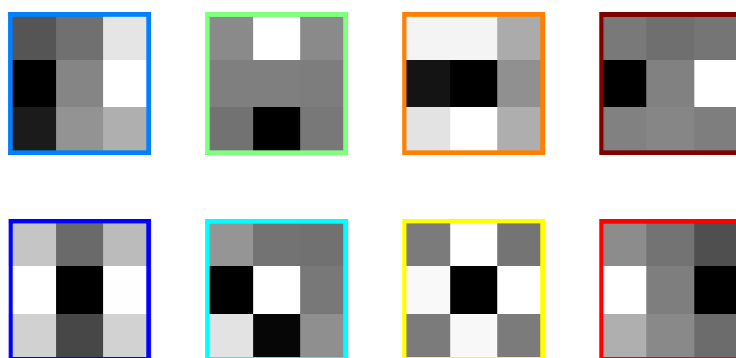
[Roth & Black '09]



[Weiss & Freeman '07]



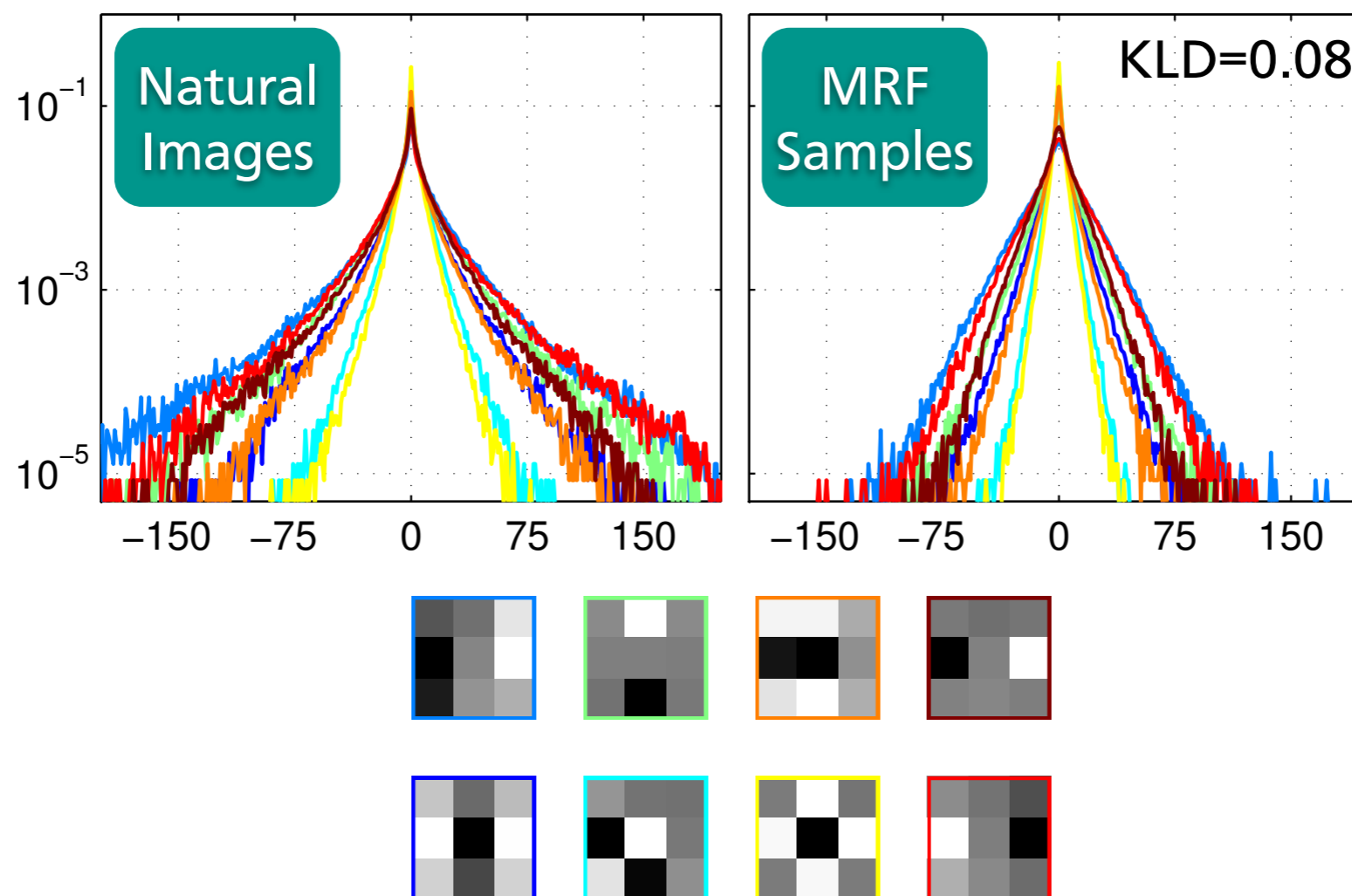
Learned linear filters



Much more peaked!

# Generative Properties of our FoE

- Filter statistics of our learned  $3 \times 3$  FoE
  - Much better than previous models
  - Room for improvement





# Image Denoising

- Image denoising assuming i.i.d. Gaussian noise with known standard deviation  $\sigma$

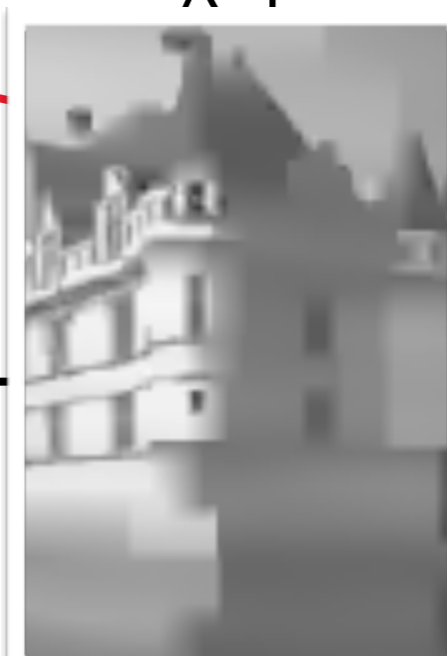
$$p(\mathbf{x}|\mathbf{y}; \Theta) \propto \mathcal{N}(\mathbf{y}; \mathbf{x}, \sigma^2 \mathbf{I}) \cdot p(\mathbf{x}; \Theta)^\lambda$$

Gaussian Likelihood     Our 3×3 FoE     Regularization weight  $\lambda$

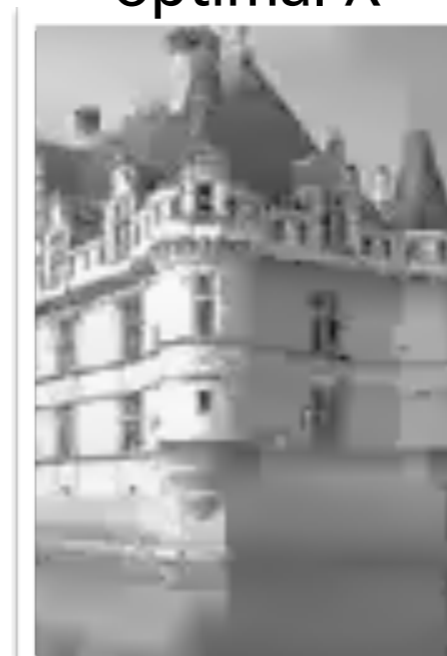


PSNR=22.18dB

MAP



PSNR=26.64dB



PSNR=29.18dB


[Roth & Black '09]  
MAP, optimal  $\lambda$



PSNR=30.06dB

# Image Denoising – MAP

- Recent works point to deficiencies of MAP [Nikolova '07, Woodford et al. '09]
- We find only **modest correlation** between:
  - Image quality of the MAP estimate
  - Generative quality of the MRF

Better generative properties  Better application performance

# Image Denoising – MMSE

- We propose to use Bayesian minimum mean squared error estimation (MMSE)

$$\hat{\mathbf{x}} = \arg \min_{\tilde{\mathbf{x}}} \int \|\tilde{\mathbf{x}} - \mathbf{x}\|^2 p(\mathbf{x}|\mathbf{y}; \Theta) d\mathbf{x} = E[\mathbf{x}|\mathbf{y}]$$

- [Levi '09] extended sampler to the posterior
  - Only used a single sample in applications
- We approximate the MMSE estimate
  - Average samples from the posterior
- We find **high correlation** between:
  - Image quality of the MMSE estimate
  - Generative quality of the MRF

Samples



average

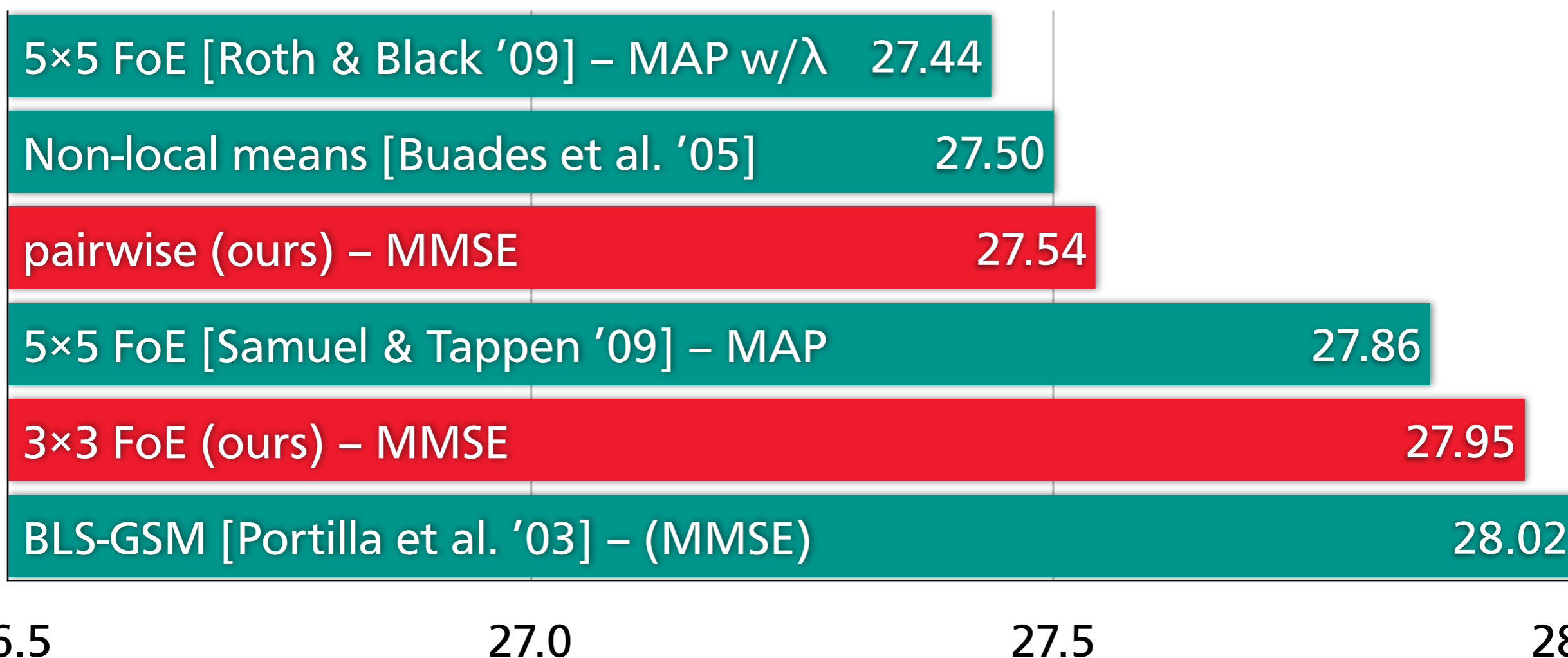


MMSE

# Image Denoising – Results

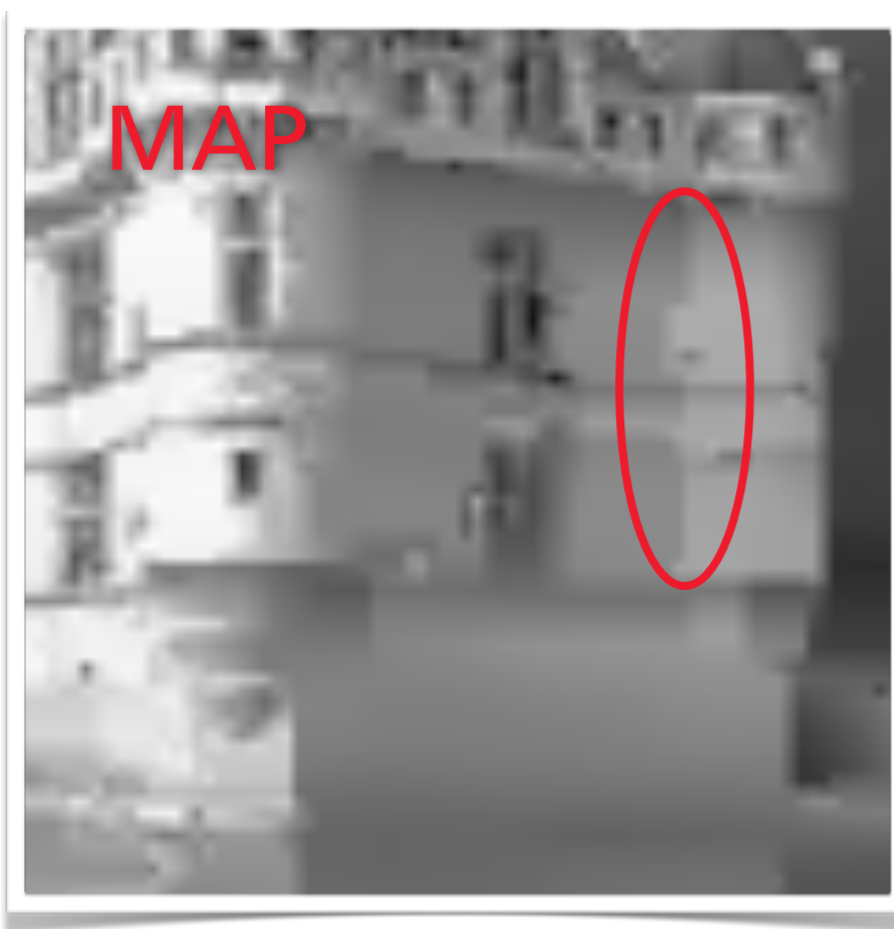
- Compared the MMSE estimate for our learned models with other popular methods

Average PSNR (dB) for 68 test images ( $\sigma = 25$ )



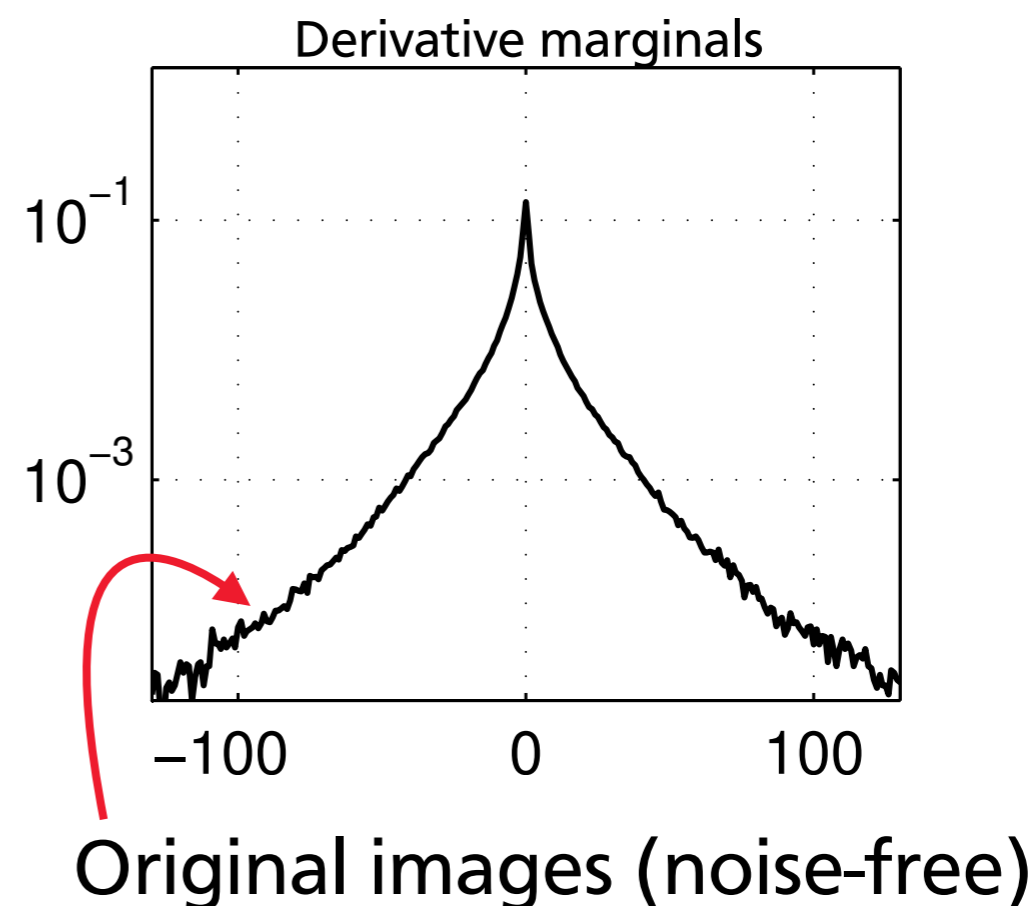
# Advantages of the MMSE

- Denoising performance highly correlated with the generative quality of the model
- No regularization weight  $\lambda$  required to perform well
- Denoised image does not exhibit incorrect statistics



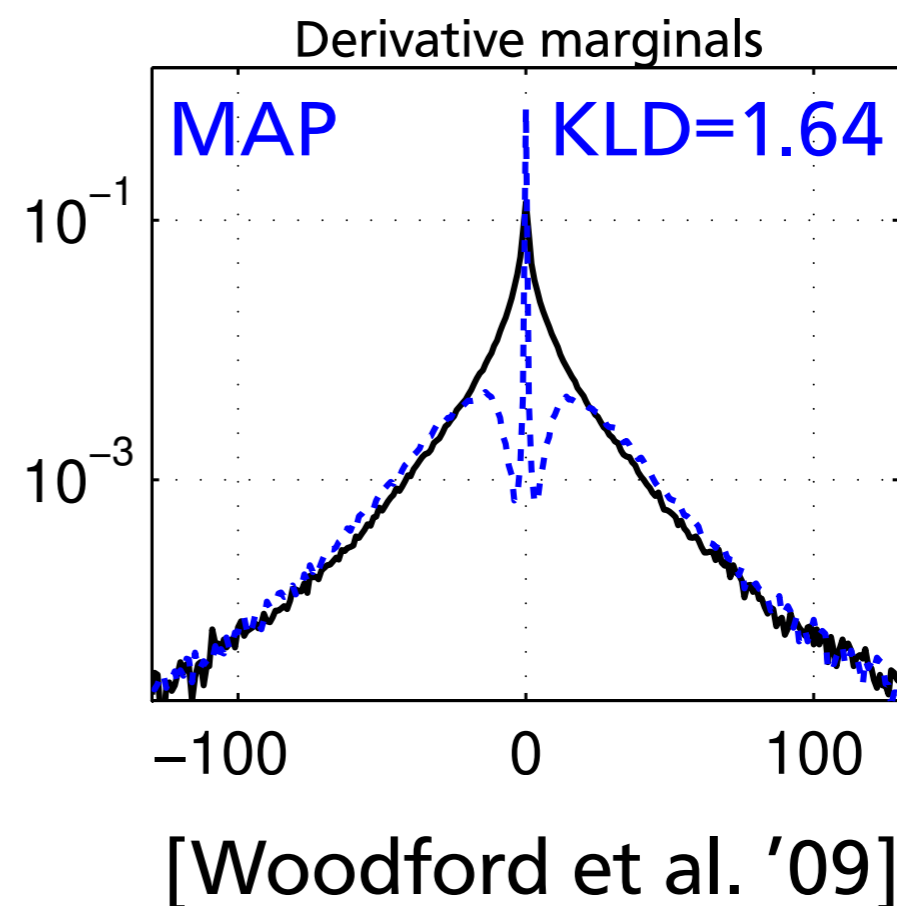
# Advantages of the MMSE

- Denoising performance highly correlated with the generative quality of the model
- No regularization weight  $\lambda$  required to perform well
- Denoised image does not exhibit incorrect statistics
  - No piecewise constant regions



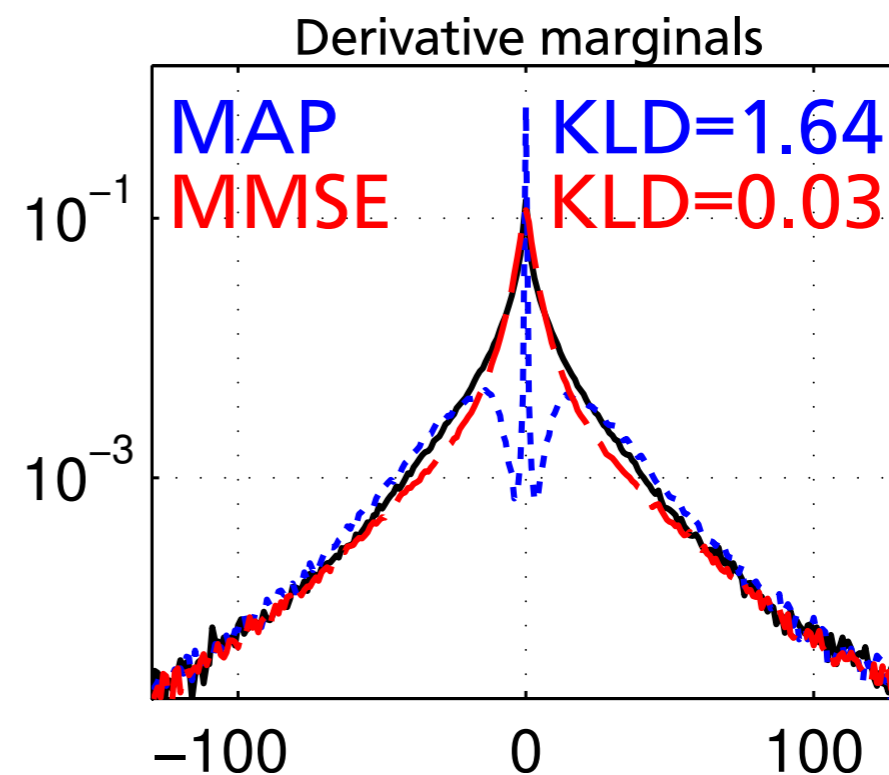
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# Advantages of the MMSE

- Denoising performance highly correlated with the generative quality of the model
- No regularization weight  $\lambda$  required to perform well
- Denoised image does not exhibit incorrect statistics
  - No piecewise constant regions
  - Works with standard MRFs





# Summary

- Evaluated MRFs through their generative properties
  - Based on a flexible framework with an efficient sampler
- Common image priors are surprisingly poor generative models
- Learned better generative MRFs (pairwise & high-order)
  - Potentials more peaked
- Sampling makes MMSE estimation practical
  - Several advantages over MAP
  - Excellent results from generative, application-neutral models

# Thanks!



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## Acknowledgments:

**Yair Weiss, Arjan Kuijper, Michael Goesele,  
Kegan Samuel, Marshall Tappen**

**Please come to our poster!**

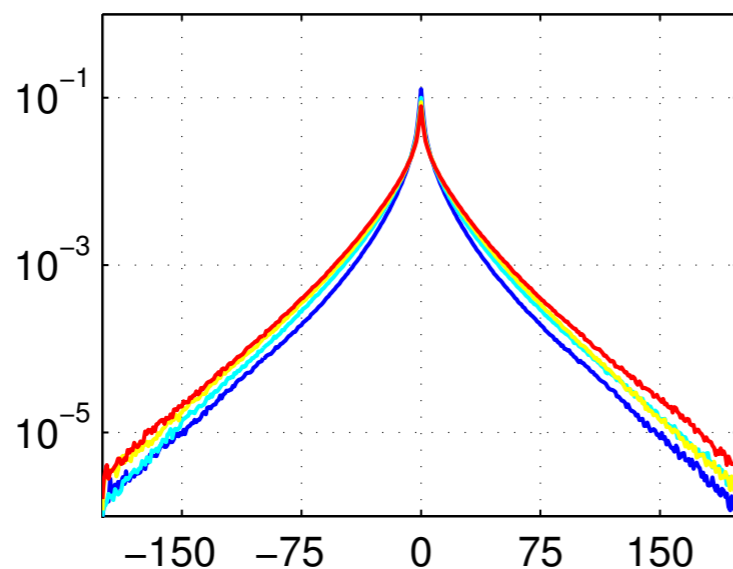
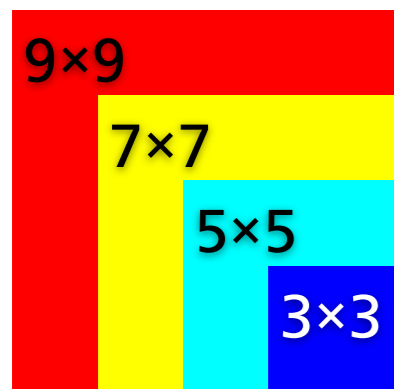
Code and models available soon at <http://bit.ly/mmse-mrf>

**Questions?**

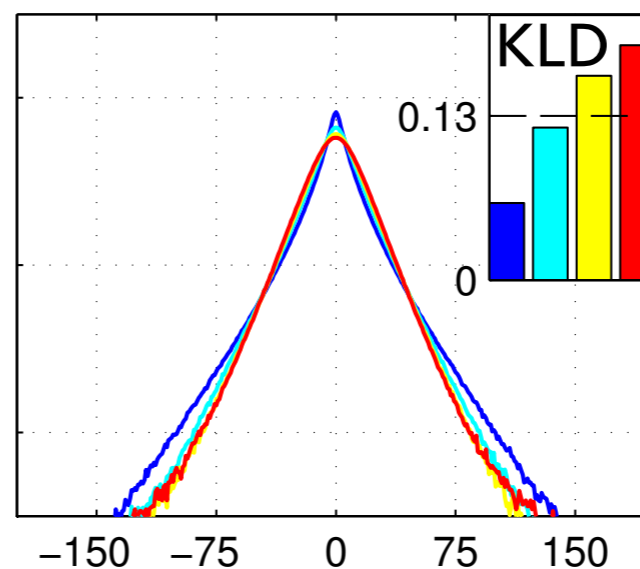


# More Generative Properties

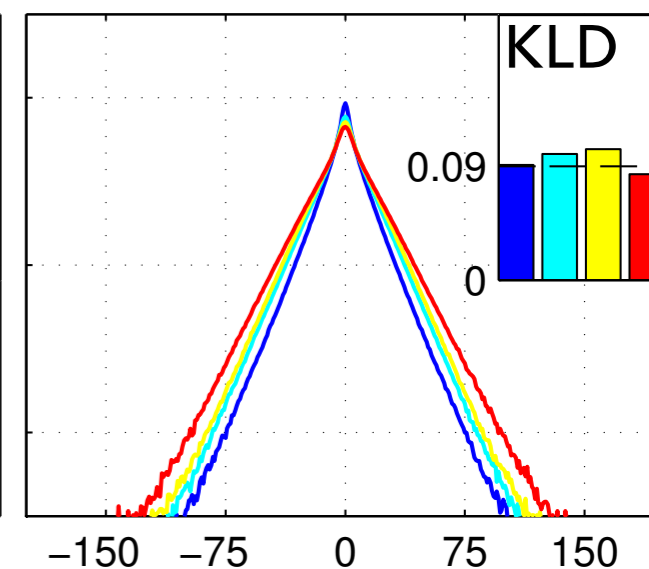
## Random filters



Natural images

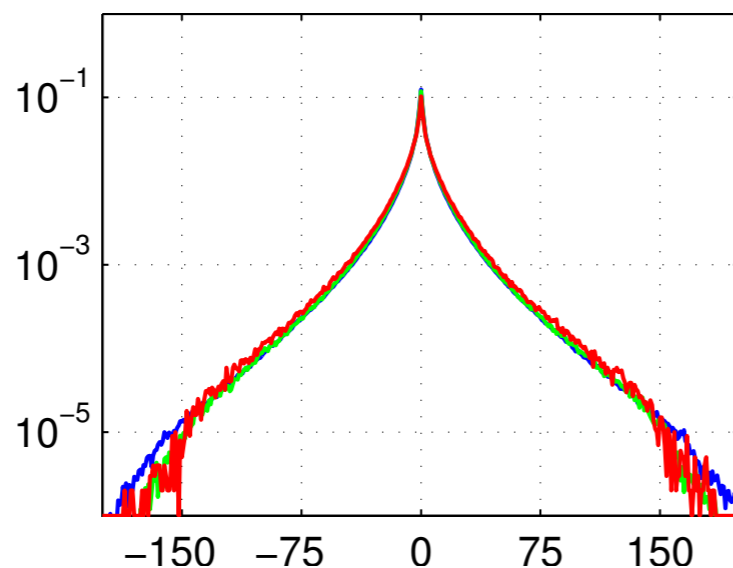
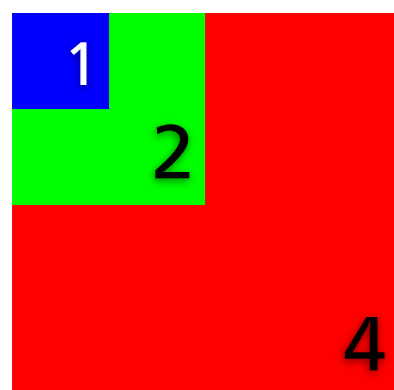


Our pairwise MRF

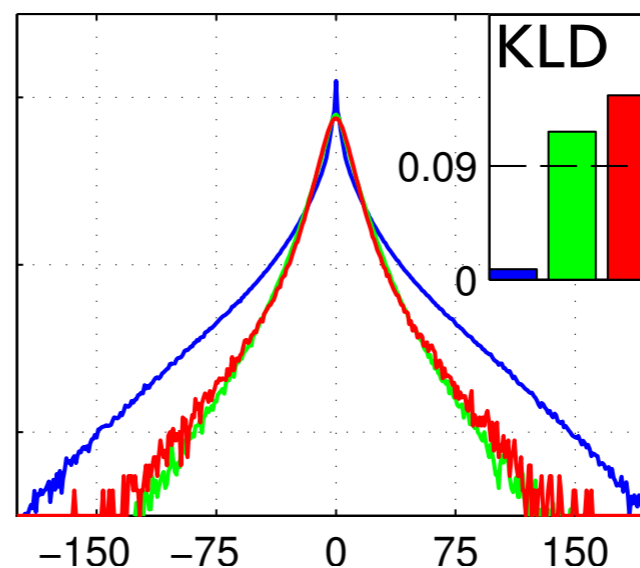


Our 3x3 FoE

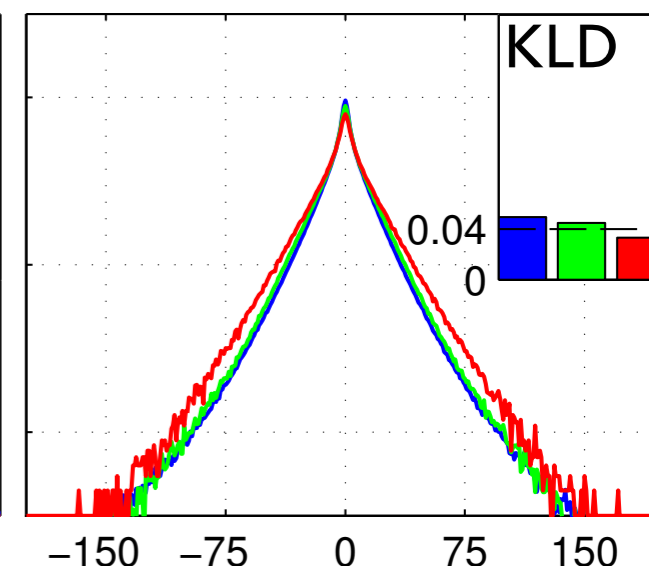
## Multiscale derivative filters



Natural images



Our pairwise MRF



Our 3x3 FoE